

# Complementarity Problems with AMPL

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## Outline

- Nash Games and Named Problems
- Complementarity Formulation
- Numerical Methods
- Intermediate AMPL
- Conclusion

## Nash Games

- Non-cooperative game played by  $n$  individuals
- Each selects strategy to optimize their objective
- Given strategies selected by other players
- Equilibrium when no improvement possible
- Characterization of two player equilibrium  $(x_1^*, x_2^*)$ :

$$x_1^* \in \begin{cases} \arg \min_{x_1 \geq 0} & f_1(x_1, x_2^*) \\ \text{subject to} & c_1(x_1) \leq 0 \end{cases}$$
$$x_2^* \in \begin{cases} \arg \min_{x_2 \geq 0} & f_2(x_1^*, x_2) \\ \text{subject to} & c_2(x_2) \leq 0 \end{cases}$$

## Economic Applications

- Bi-matrix games
- Cournot duopoly models
- General equilibrium models
- Walrasian equilibrium
- Arrow-Debreau models

## Block Gauss-Seidel Method

1. For each player  $p$

(a) Solve optimization problem

$$\hat{x}_p \in \begin{cases} \arg \min_{x_p \geq 0} & f_p(\bar{x}_p) \\ \text{subject to} & c_p(x_p) \leq 0 \end{cases}$$

with  $\bar{x}_p = (x_1^*, \dots, x_{p-1}^*, x_p, x_{p+1}^*, \dots, x_n^*)$

(b) Update  $x_p^* = \hat{x}_p$

2. Check convergence and repeat

- Cannot be applied to every problem
- Method may not converge
- Linear convergence rate

## Oligopoly Model

- Each firm chooses output to maximize profit
  - $\alpha$  and  $\eta$  are parameters
  - $c_f$  is unit cost for each firm
  - $u$  is the utility function

$$u = \left( 1 + \sum_{f \in F} x_f^\alpha \right)^{\frac{\eta}{\alpha}}$$

- $x_f$  is output for each firm
- In particular, for each  $f \in F$

$$x_f^* \in \arg \max_{x_f \geq 0} \left( \frac{\partial u}{\partial x_f} - c_f \right) x_f$$

## Model Definition: oligopoly.mod

```
set FIRMS;                                # Firms in problem

param c {FIRMS};                          # Unit cost
param alpha > 0;                          # Constants
param eta > 0;

var x {FIRMS} >= 0 default 0.1;           # Output
var u =                                    # Utility
    (1 + sum {f in FIRMS} x[f]^alpha)^(eta/alpha);
var du {f in FIRMS} =                     # Price
    eta * (1 + sum {g in FIRMS} x[g]^alpha)^(eta/alpha - 1) * x[f]^(alpha - 1);

maximize profit {f in FIRMS}:
    (du[f] - c[f]) * x[f];

problem opt {f in FIRMS}: profit[f], x[f], du[f];
```

## Data Definition: oligopoly.dat

```
param: FIRMS : c :=
```

```
    1      0.07
```

```
    2      0.08
```

```
    3      0.09;
```

```
param alpha := 0.999;
```

```
param eta := 0.2;
```



## Execution Commands: oligopoly.cmd

```
# Load model and data
model oligopoly.mod;
data oligopoly.dat;

# Specify solver and options
option solver "minos";
option minos_options "outlev=1";

# Simple Block Gauss-Seidel method
for {iter in 1..10} {
  for {f in FIRMS} {
    problem opt[f];
    solve;
  }
}

printf {f in FIRMS} "Output for firm %2d: % 5.4e\n", f, x[f] > oligopoly.out;
```

## Output File: oligopoly.out

```
Output for firm 1: 8.3734e-01  
Output for firm 2: 5.0719e-01  
Output for firm 3: 1.7923e-01
```

## Wardropian Equilibrium with Congestion

- Route commodities through network
  - $\mathcal{N}$  denotes the nodes and  $\mathcal{A} \subseteq \mathcal{N} \times \mathcal{N}$  the arcs
  - $\mathcal{K}$  denotes the commodities
  - $\alpha, \beta$  are the congestion parameters
  - $b$  denotes the supply and demand
- Minimize time for each commodity  $k$

$$\begin{aligned} \min_{x_{*,*,k} \geq 0} \quad & \sum_{(i,j) \in \mathcal{A}} \alpha_{i,j} \left( \sum_{k \in \mathcal{K}} x_{i,j,k} \right) + \beta_{i,j} \left( \sum_{k \in \mathcal{K}} x_{i,j,k} \right)^4 \\ \text{subject to} \quad & \sum_{(i,j) \in \mathcal{A}} x_{i,j,k} \leq \sum_{(j,i) \in \mathcal{A}} x_{j,i,k} + b_{i,k} \quad \forall i \in \mathcal{N} \end{aligned}$$

## Model Definition: wardrop.mod

```
set NODES;                                # Nodes in network
set ARCS within NODES cross NODES;        # Arcs in network
set COMMODITIES := 1..3;                   # Commodities

param b {NODES, COMMODITIES} default 0;    # Supply/demand
param alpha {ARCS} >= 0;                  # Linear part
param beta {ARCS} >= 0;                    # Nonlinear part

var x {ARCS, COMMODITIES} >= 0;           # Flow on arcs
var f {(i,j) in ARCS} =                   # Total flow
    sum {k in COMMODITIES} x[i,j,k];

minimize time {k in COMMODITIES}:
    sum {(i,j) in ARCS} (alpha[i,j]*f[i,j] + beta[i,j]*f[i,j]^4);

subject to
    conserve {i in NODES, k in COMMODITIES}:
        sum {(i,j) in ARCS} x[i,j,k] <= sum{(j,i) in ARCS} x[j,i,k] + b[i,k];

problem player {k in COMMODITIES}: time[k], {i in NODES} conserve[i,k],
    {(i,j) in ARCS} x[i,j,k], f;
```

## Data Definition: wardrop.dat

```
set NODES := 1 2 3 4 5;
```

```
param: ARCS : alpha beta =
```

1 2	1	0.5
1 3	1	0.4
2 3	2	0.7
2 4	3	0.1
3 2	1	0.0
3 4	4	0.5
4 1	5	0.0
4 5	2	0.1
5 2	0	1.0;

```
let b[1,1] := 7;      # Node 1, Commodity 1 supply
let b[4,1] := -7;    # Node 4, Commodity 1 demand
let b[2,2] := 3;     # Node 2, Commodity 2 supply
let b[5,2] := -3;    # Node 5, Commodity 2 demand
let b[3,3] := 5;     # Node 1, Commodity 3 supply
let b[1,3] := -5;    # Node 4, Commodity 3 demand
```

## Execution Commands: wardrop.cmd

```
# Load model and data
model wardrop.mod;
data wardrop.dat;

# Specify solver and options
option solver "minos";
option minos_options "outlev=1";

# Simple Block Gauss-Seidel method
for {iter in 1..90} {
  for {k in COMMODITIES} {
    problem player[k];
    solve;
  }
}

for {k in COMMODITIES} {
  printf "Commodity: %d\n", k > wardrop.out;
  printf {(i,j) in ARCS: x[i,j,k] > 0} "%d.%d = % 5.4e\n", i, j, x[i,j,k] > wardrop.out;
  printf "\n" > wardrop.out;
}
```

## Output File: wardrop.out

Commodity: 1

1.2 = 3.3775e+00

1.3 = 3.6225e+00

2.4 = 4.4169e+00

3.2 = 1.0394e+00

3.4 = 2.5831e+00

Commodity: 2

2.4 = 3.0000e+00

4.5 = 3.0000e+00

Commodity: 3

2.4 = 2.0480e+00

3.2 = 2.0480e+00

3.4 = 2.9520e+00

4.1 = 5.0000e+00

## Bimatrix Game

- Player 1

$$\begin{aligned} \min_{p \geq 0} \quad & p^T \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} q \\ \text{subject to} \quad & e^T p = 1 \end{aligned}$$

- Player 2

$$\begin{aligned} \min_{q \geq 0} \quad & p^T \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} q \\ \text{subject to} \quad & e^T q = 1 \end{aligned}$$

- Gauss-Seidel cycles

$$p = (0, 1) \Rightarrow q = (1, 0) \Rightarrow p = (1, 0) \Rightarrow q = (0, 1) \Rightarrow p = (0, 1)$$



## Optimization Theory Review

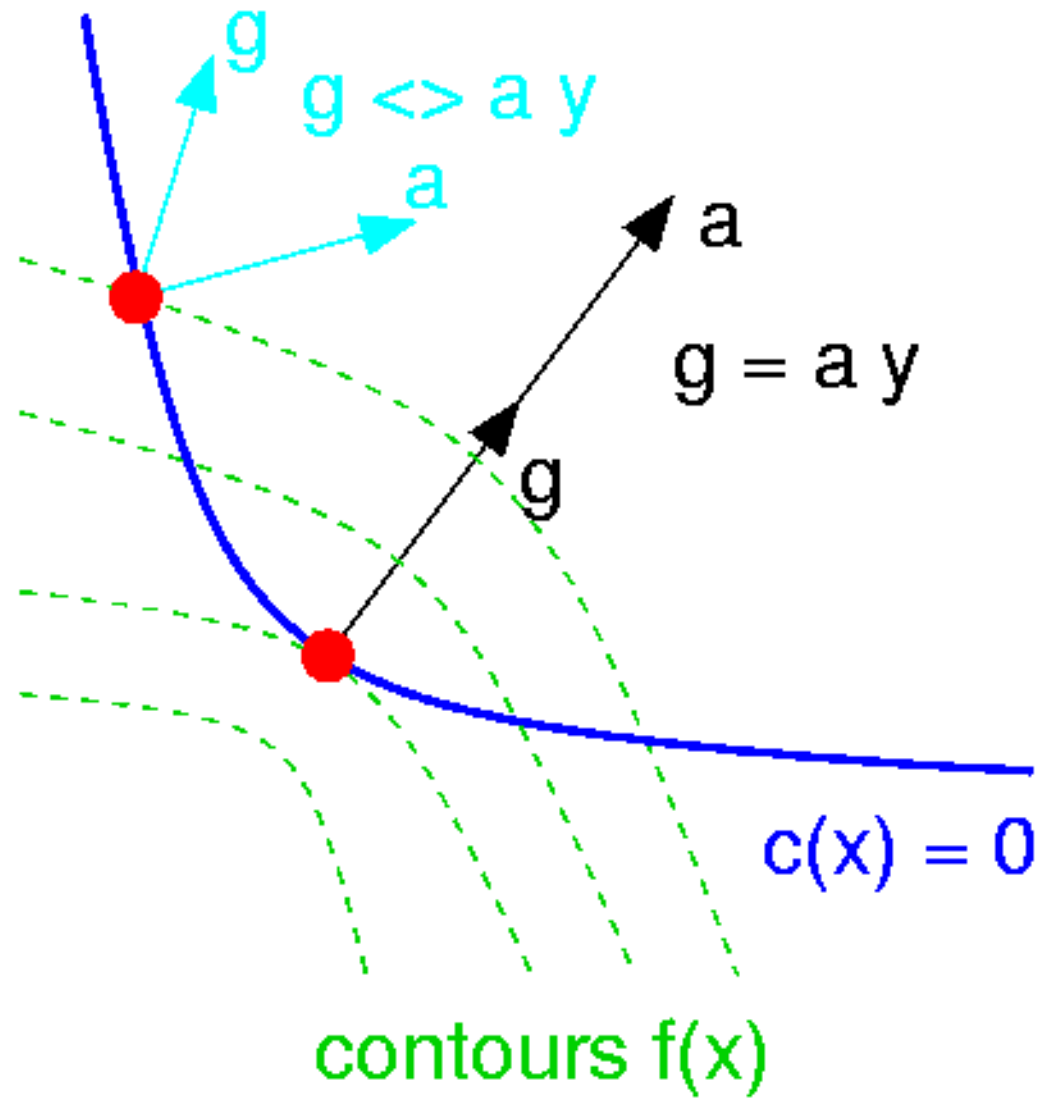
- Assume convex optimization problem
  - $f(\cdot)$  and  $c(\cdot)$  are convex function
  - Constraint qualification satisfied
- Then first-order conditions are necessary and sufficient

$$\begin{array}{l} \min_{x \geq 0} \quad f(x) \\ \text{subject to} \quad c(x) \leq 0 \end{array} \Leftrightarrow \begin{array}{l} 0 \leq x \perp \nabla f(x) + \lambda^T \nabla c(x) \geq 0 \\ 0 \leq \lambda \perp -c(x) \geq 0 \end{array}$$

- Notation:  $0 \leq a \perp b \geq 0 \Leftrightarrow a \geq 0, b \geq 0, ab = 0$
- Nonlinear complementarity problem

$$0 \leq x \perp F(x) \geq 0$$

# Illustration



## Application to Nash Games

- Assume each player solves a convex problem
  - $f_1(\cdot, x_2)$  is convex for all  $x_2$
  - $f_2(x_1, \cdot)$  is convex for all  $x_1$
  - $c_1(\cdot)$  and  $c_2(\cdot)$  are convex functions
  - Constraint qualification satisfied
- Stacked first-order conditions characterize equilibrium

$$0 \leq x_1 \quad \perp \quad \nabla_{x_1} f_1(x_1, x_2) + \lambda_1^T \nabla c_1(x_1) \geq 0$$

$$0 \leq \lambda_1 \quad \perp \quad -c_1(x_1) \geq 0$$

$$0 \leq x_2 \quad \perp \quad \nabla_{x_2} f_2(x_1, x_2) + \lambda_2^T \nabla c_2(x_2) \geq 0$$

$$0 \leq \lambda_2 \quad \perp \quad -c_2(x_2) \geq 0$$

- Square nonlinear complementarity problem

## Numerical Methods I

- Josephy-Newton Method for  $0 \leq x \perp F(x) \geq 0$

$$0 \leq x^{k+1} \perp \nabla F(x^k)(x^{k+1} - x^k) + F(x^k) \geq 0$$

- PATH (AMPL and GAMS)
  - \* Semismooth merit function
  - \* Nonmonotone line search
  - \* Modified Lemke method
  - \* Crash technique
- MILES (GAMS only)

## Numerical Methods II

- Semismooth Methods

- NCP Functions  $\phi : \mathfrak{R}^2 \rightarrow \mathfrak{R}$

$$\phi(a, b) = 0 \Leftrightarrow 0 \leq a \perp b \geq 0$$

- \* Fischer-Burmeister function

$$\phi(a, b) = a + b - \sqrt{a^2 + b^2}$$

- \* Reformulate complementarity problem

$$\Phi(x) = [\phi(x_i, F_i(x))]$$

- Apply Newton method to  $\Phi(x) = 0$

$$x^{k+1} = H_k^{-1}(x^k - \Phi(x^k))$$

$$H \in \partial\Phi(x)$$

## Numerical Methods III

- Reformulate as optimization problem
  - Minimize complementarity error

$$\begin{aligned} \min_{x \geq 0, s \geq 0} \quad & x^T s \\ \text{subject to} \quad & s = F(x) \end{aligned}$$

- Many possible formulations

$$\begin{aligned} \min_{x \geq 0, s \geq 0} \quad & 0 \\ \text{subject to} \quad & s = F(x) \\ & x^T s \leq 0 \end{aligned}$$

- Interior-point methods for special cases

## Oligopoly Model Revisited

- Each firm chooses output to maximize profit
- $u$  is the utility function

$$u = \left( 1 + \sum_{f \in F} x_f^\alpha \right)^{\frac{\eta}{\alpha}}$$

- For each  $f \in F$

$$x_f^* \in \arg \max_{x_f \geq 0} \left( \frac{\partial u}{\partial x_f} - c_f \right) x_f$$

- Complementarity problem

$$0 \leq x_f \perp c_f - \frac{\partial u}{\partial x_f} - \frac{\partial^2 u}{\partial x_f^2} x_f \geq 0$$

## Model Definition: oligcomp.mod

```
set FIRMS;                                # Firms in problem

param c {FIRMS};                          # Unit cost
param alpha > 0;                          # Constants
param eta > 0;

var x {FIRMS} default 0.1;                # Output (no bounds!)

var s = 1 + sum {f in FIRMS} x[f]^alpha;  # Summation term
var u = s^(eta/alpha);                    # Utility
var du {f in FIRMS} =                    # Price
    eta * s^(eta/alpha - 1) * x[f]^(alpha - 1);
var dudu {f in FIRMS} =                  # Derivative
    eta * (eta - alpha) * s^(eta/alpha - 2) * x[f]^(2 * alpha - 2) +
    eta * (alpha - 1) * s^(eta/alpha - 1) * x[f]^(alpha - 2);

subject to
compl {f in FIRMS}:
    0 <= x[f] complements c[f] - du[f] - dudu[f]*x[f] >= 0;
```



## Execution Commands: oligcomp.cmd

```
# Load model and data
model oligcomp.mod;
data oligcomp.dat;

# Specify solver and options
option presolve 0;
option solver "kestrel";
option kestrel_options "solver=path";

# Solve complementarity problem
solve;

printf {f in FIRMS} "Output for firm %2d: % 5.4e\n", f, x[f] > oligcomp.out;
```

## Output File: oligcomp.out

```
Output for firm 1: 8.3735e-01  
Output for firm 2: 5.0720e-01  
Output for firm 3: 1.7921e-01
```

## Equilibrium for Endowment Economy I

- Economy with  $n$  agents and  $m$  commodities
  - $e \in \mathfrak{R}^{n \times m}$  are the endowments
  - $\alpha, \beta \in \mathfrak{R}^{n \times m}$  are the utility parameters
  - $x \in \mathfrak{R}^{n \times m}$  is the amount consumed
  - $p \in \mathfrak{R}^m$  is the commodity price

## Equilibrium for Endowment Economy II

- Agent  $i$  maximizes utility with budget constraint

$$\begin{aligned} \max_{x_{i,*} \geq 0} \quad & \sum_{k=1}^n \frac{\alpha_{i,k} (1 + x_{i,k})^{1-\beta_{i,k}}}{1 - \beta_{i,k}} \\ \text{subject to} \quad & \sum_{k=1}^n p_k (x_{i,k} - e_{i,k}) \leq 0 \end{aligned}$$

- Market  $k$  sets price for commodity

$$0 \leq p_k \quad \perp \quad \sum_{i=1}^n (e_{i,k} - x_{i,k}) \geq 0$$

- Square complementarity problem

## Model Definition I: cge.mod

```
set AGENTS;                # Agents
set COMMODITIES;          # Commodities

param e {AGENTS, COMMODITIES} >= 0, default 1; # Endowment

param alpha {AGENTS, COMMODITIES} > 0;        # Utility parameters
param beta {AGENTS, COMMODITIES} > 0;

var x {AGENTS, COMMODITIES};                  # Consumption (no bounds!)
var l {AGENTS} default 1;                     # Multipliers (no bounds!)
var p {COMMODITIES} default 1;                # Prices (no bounds!)
```

## Model Definition II: cge.mod

```
var du {i in AGENTS, k in COMMODITIES} =          # Marginal prices
    alpha[i,k] / (1 + x[i,k])^beta[i,k];

subject to
    optimality {i in AGENTS, k in COMMODITIES}:
        0 <= x[i,k] complements -du[i,k] + p[k] * l[i] >= 0;

    budget {i in AGENTS}:
        0 <= l[i]    complements sum {k in COMMODITIES} p[k]*(e[i,k] - x[i,k]) >= 0;

    market {k in COMMODITIES}:
        0 <= p[k]    complements sum {i in AGENTS} (e[i,k] - x[i,k]) >= 0;
```

## Data Definition: cge.dat

```
set AGENTS := Jorge, Sven, Todd;  
set COMMODITIES := Books, Cars, Food, Pens;
```

```
param alpha : Books Cars Food Pens :=  
    Jorge      1    1    1    1  
    Sven       1    2    3    4  
    Todd       2    1    1    5;
```

```
param beta (tr): Jorge Sven Todd :=  
    Books      1.5  2    0.6  
    Cars       1.6  3    0.7  
    Food       1.7  2    2.0  
    Pens       1.8  2    2.5;
```

## Execution Commands: cge.cmd

```
# Load model and data
model cge.mod;
data cge.dat;

# Specify solver and options
option presolve 0;
option solver "kestrel";
option kestrel_options "solver=path";

# Solve the instance
solve;

# Output results
printf {i in AGENTS, k in COMMODITIES} "%5s %5s: % 5.4e\n", i, k, x[i,k] > cge.out;
printf "\n" > cge.out;
printf {k in COMMODITIES} "%5s: % 5.4e\n", k, p[k] > cge.out;
```



## Output File: cge.out

Jorge Books: 8.9825e-01  
Jorge Cars: 1.4651e+00  
Jorge Food: 1.2021e+00  
Jorge Pens: 6.8392e-01  
Sven Books: 2.5392e-01  
Sven Cars: 7.2054e-01  
Sven Food: 1.6271e+00  
Sven Pens: 1.4787e+00  
Todd Books: 1.8478e+00  
Todd Cars: 8.1431e-01  
Todd Food: 1.7081e-01  
Todd Pens: 8.3738e-01

Books: 1.0825e+01  
Cars: 6.6835e+00  
Food: 7.3983e+00  
Pens: 1.1081e+01

## Execution Commands: cgenum.cmd

```
# Load model and data
model cge.mod;
data cge.dat;

# Specify solver and options
option presolve 0;
option solver "kestrel";
option kestrel_options "solver=path";

# Solve the instance
drop market['Books'];
fix p['Books'] := 1;
solve;

# Output results
printf {i in AGENTS, k in COMMODITIES} "%5s %5s: % 5.4e\n", i, k, x[i,k] > cgenum.out;
printf "\n" > cgenum.out;
printf {k in COMMODITIES} "%5s: % 5.4e\n", k, p[k] > cgenum.out;
```

## Output File: cgenum.out

```
Jorge Books: 8.9825e-01
Jorge Cars: 1.4651e+00
Jorge Food: 1.2021e+00
Jorge Pens: 6.8392e-01
Sven Books: 2.5392e-01
Sven Cars: 7.2054e-01
Sven Food: 1.6271e+00
Sven Pens: 1.4787e+00
Todd Books: 1.8478e+00
Todd Cars: 8.1431e-01
Todd Food: 1.7081e-01
Todd Pens: 8.3738e-01
```

```
Books: 1.0000e+00
Cars: 6.1742e-01
Food: 6.8345e-01
Pens: 1.0237e+00
```

## Extensions

- Mixed complementarity problems

$$\ell \leq x \leq u \quad \perp \quad F(x)$$

- Nonlinear systems of equations

$$x \text{ free} \quad \perp \quad F(x) = 0$$

- Generalized relationships

$$0 \leq G(x) \quad \perp \quad F(x) \geq 0$$

- Slacks and constraints added
- Reformulated as mixed complementarity problem

## Pitfalls

- Nonsquare systems
  - Side variables
  - Side constraints
- Nonideal orientation for equations
  - Skew symmetry preferred
  - Proximal point perturbation
- AMPL presolve
  - `option presolve 0;`

## Conclusion

- Algorithms can be written in AMPL
- Complementarity problems are useful
  - Express equations and inequalities
  - Determine activities
- Some algorithms for solving them
  - Commercially available
  - Usable through NEOS